

Stability Analysis

let

A = Exact Analytical Solution

D = Exact Solution for discretized Equation

N = Computer Solution for discretized Equation

⇒ A-D = truncation Error

⇒ N-D = round-off Error = ϵ

$$N = D + \epsilon$$

** Studying the Equation $\frac{\partial u}{\partial t} = \nu \frac{\partial^2 u}{\partial y^2}$

$$\Rightarrow \frac{u_i^{n+1} - u_i^n}{\Delta t} = \nu \frac{u_{i+1}^n - 2u_i^n + u_{i-1}^n}{(\Delta y)^2} + O[\Delta t, \Delta y^2]$$

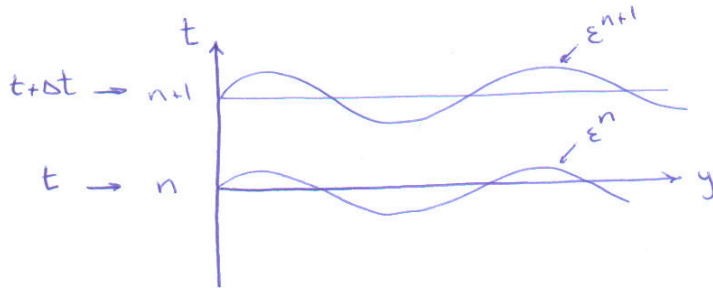
$$\Rightarrow \frac{(\phi + \epsilon)_i^{n+1} - (\phi + \epsilon)_i^n}{\Delta t} = \nu \frac{(\phi + \epsilon)_{i+1}^n - 2(\phi + \epsilon)_i^n + (\phi + \epsilon)_{i-1}^n}{(\Delta y)^2}$$

$$\Rightarrow \frac{\epsilon_i^{n+1} - \epsilon_i^n}{\Delta t} = \nu \frac{\epsilon_{i+1}^n - 2\epsilon_i^n + \epsilon_{i-1}^n}{(\Delta y)^2}$$

∴ Round off error is a function of t & y

*** Von Neumann Stability Analysis ∴ -

$$\xi(t, y) = e^{at} e^{ik_m y}$$



$$\begin{aligned} \therefore e^{a(t+\Delta t)} e^{ik_m y} - e^{at} e^{ik_m y} &= \frac{\partial \Delta t}{\Delta y^2} * e^{at} \left[e^{ik_m(y+\Delta y)} - 2e^{ik_m y} + e^{ik_m(y-\Delta y)} \right] \\ \text{let } r &= \frac{\partial \Delta t}{\Delta y^2}, \quad \beta = k_m \Delta y \end{aligned}$$

$$\Rightarrow e^{a\Delta t} - 1 = r \left[e^{ik_m \Delta y} - 2 + e^{-ik_m \Delta y} \right]$$

$$\Rightarrow e^{a\Delta t} - 1 = r \left[e^{i\beta} + e^{-i\beta} - 2 \right]$$

$$= r \left[\cos \beta + i \sin \beta + \cos \beta - i \sin \beta - 2 \right]$$

$$= 2r \left[\cos \beta - 1 \right]$$

$$= 2r \left[-2 \sin^2 \frac{\beta}{2} \right] = -4r \sin^2 \frac{\beta}{2}$$

$$\circ \circ \quad e^{a \Delta t} = 1 - 4r \sin^2 \frac{\beta}{2}$$

$$\Rightarrow \quad \varepsilon_i^n = e^{at} e^{i\beta}, \quad \varepsilon_i^{n+1} = e^{a(t+\Delta t)} e^{i\beta}$$

$$\circ \circ \quad \text{Amplification factor} = \frac{\varepsilon_i^{n+1}}{\varepsilon_i^n} = e^{a \Delta t} \begin{cases} > 1 & \text{Unstable} \\ < 1 & \text{Stable} \end{cases}$$

$$\circ \circ \quad \left| 1 - 4r \sin^2 \frac{\beta}{2} \right| \leq 1$$

Stability Condition :-

$$r \geq 0 \quad \Rightarrow \quad \frac{\Delta t}{\Delta y^2} \geq 0$$

$$\& \quad r \leq \frac{1}{2 \sin^2 \frac{\beta}{2}} \quad \Rightarrow \quad \Delta t \leq \frac{1}{2} \frac{\Delta y^2}{\nu}$$

$\circ \circ$ for stability use smaller Δt

N.B.

Explicit methods only suffers stability problems.